

Accessories

Connection of motor and encoder	Couplings	Bellows and spring washer couplings
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Bellows couplings provide cost-effective connection of the motor and encoder. They are also able to correct any angular errors between the drive and encoder.

Spring washer couplings are used with high speeds.

Order code	8.0000	. 1 X	02	. XX XX
Couplings	Type	a	b	c

a *Type of coupling*

- 1 = Bellows-type \varnothing 19 mm [0.75"]
- 2 = Bellows-type \varnothing 15 mm [0.59"]
- 3 = Spring washer type, \varnothing 30 mm [1.18"], one-part
- 4 = Spring washer type, \varnothing 30 mm [1.18"], three part, plug-in
- 5 = Bellows-type \varnothing 25 mm [0.98"]

b *Bore diameter d1*
(see technical data)

Note:
for the bore diameter
d1 = 3/8" please enter Code A1
d1 = 1/4" please enter Code A2

Example a) : d1 = 10 mm [0.39"] and d2 = 12 mm [0.47"]
Order No. = 8.0000.1X01.1012

Example b) : d1 = 3/8" and d2 = 10 mm [0.39"]
Order No. = 8.0000.1X01.A110

c *Bore diameter d2*
(see technical data)

Technical data										
Type	8.0000.1102.XXXX		8.0000.1202.XXXX		8.0000.1302.XXXX		8.0000.1402.XXXX		8.0000.1502.XXXX	
Max. speed	min ⁻¹	10000	10000	12000	12000	10000				
Max. torque	Ncm	120	40	80	60	200				
Max. radial displacement	radial	mm	\pm 0.3	\pm 0.25	\pm 0.4	\pm 0.3	\pm 0.35			
	axial	mm	\pm 0.5	\pm 0.45	\pm 0.4	\pm 0.4	\pm 0.54			
	angular	-	\pm 4°	\pm 4°	\pm 3°	\pm 2,5°	\pm 4°			
Torsion spring stiffness	Nm/rad	150	85	150	30	183				
Radial spring stiffness	N/mm	10	20	6	40	17.8				
Moment of inertia	gcm ²	9.5	2.1	19	35	20				
Max. tightening torque	Ncm	150	70	80	80	120				
Working temperature		-30°C ... +120°C [-22°F ... +248°F]	-30°C ... +120°C [-22°F ... +248°F]	-30°C ... +120°C [-22°F ... +248°F]	-10°C ... +80°C [+14°F ... +176°F]	-30°C ... +120°C [-22°F ... +248°F]				
Weight approx.		16 g [0.56 oz]	6.5 g [0.23 oz]	16 g [0.56 oz]	30 g [1.06 oz]	24 g [0.85 oz]				
Material	flange	Al, anodised	Al, anodised	Al, anodised	Al, anodised	Al, anodised				
	Bellow or spring washer/casing	stainless steel	stainless steel	stainless steel	PA 6.6 gf.	stainless steel				
Diameter d/d1 from ... to	mm [inch]	3...12 [0.12...0.47]	3...9 [0.12...0.35]	3...8 [0.12...0.32]	4...16 [0.16...0.47]	3...16 [0.12...0.63]				
Standard bore diameter	(d1 / d2) mm [inch]	12 / 12 [0.47...0.47]	08 / 06 [0.32...0.24]	06 / 06 [0.24...0.24]	12 / 12 [0.47...0.47]	15 / 12 [0.59...0.47]				
		12 / 10 [0.47...0.39]	06 / 06 [0.24...0.24]	12 / 10 [0.47...0.39]	14 / 12 [0.55...0.47]					
		10 / 10 [0.39...0.39]	06 / 04 [0.24...0.16]	10 / 10 [0.39...0.39]	14 / 10 [0.55...0.39]					
		10 / 08 [0.39...0.32]	04 / 04 [0.16...0.16]	10 / 06 [0.39...0.24]	10 / 10 [0.39...0.39]					
		10 / 06 [0.39...0.24]		06 / 06 [0.24...0.24]	06 / 06 [0.24...0.24]					
		08 / 08 [0.32...0.32]		1/4" / 10						
		06 / 06 [0.24...0.24]		1/4" / 06						

Description and applications

Manufacturing and installation tolerances as well as the effects of temperature cause alignment errors between shafts in drive engineering which can sometimes lead to extreme overload on the bearings.

This may result in increased wear of the bearings and may lead to premature failure of the encoder. By using couplings, these alignment errors can be compensated, thereby reducing the load on the bearings to a minimum. A distinction should be made between three different kinds of alignment error: radial, angular and axial displacement.

Whilst with torsion-free but flexible shaft couplings, axial shaft displacements produce only static forces in the coupling, radial and angular displacements produce alternating stresses, restoring forces and moments which may have an impact on adjoining components (shaft bearings).

Depending on the type of coupling, particular attention should be paid to radial shaft displacement which should be kept to a minimum.

Accessories

Connection of motor and encoder

Couplings

Bellows and spring washer couplings

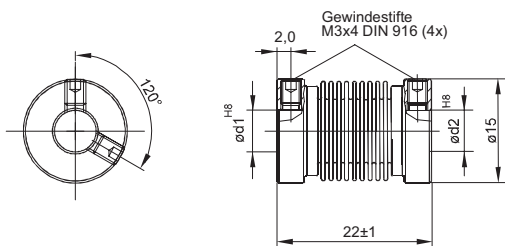
Metal bellows-type couplings (.1102, .1202 and .1502)

Metal bellows-type couplings are recommended as an inexpensive type of coupling. They are also suitable for compensating larger angle displacements.

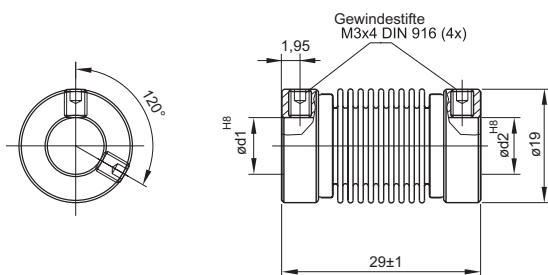
Dimensions

Dimensions in mm

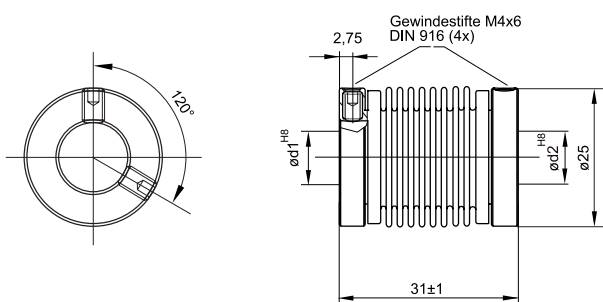
Bellows-type coupling $\varnothing 15$ [0.59]
(8.0000.1202.XXXX)



Bellows-type coupling $\varnothing 19$ [0.75]
(8.0000.1102.XXXX)



Bellows-type coupling $\varnothing 25$ [0.98]
(8.0000.1502.XXXX)



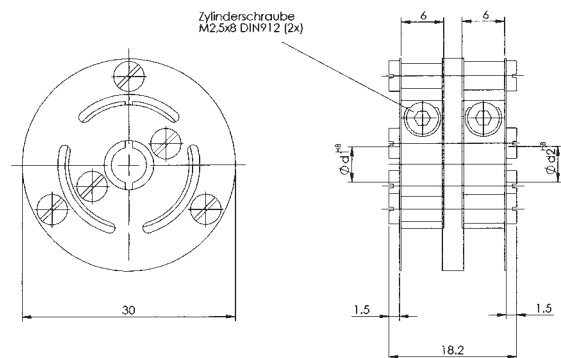
Installation instructions

1. Check shaft for displacement; see technical data for details.
2. Align and adjust coupling on shafts.
3. Tighten locking screws carefully. Avoid overtightening.
4. During installation protect the coupling from damage and from overbending.

Spring washer-type couplings (.1302 and .1402)

Spring washer-type couplings are used mainly in those cases where high speeds and smaller angular displacements are involved. For applications where electrical insulation between rotary encoder and drive is required, the electrically insulating spring washer-type coupling should be used.

Spring washer-type coupling, one-part
(8.0000.1302.XXXX)



Spring washer-type coupling, three part, plug-in
(8.0000.1402.XXXX)

