



2-phase stepping motor

# 42mm sq. (1.65inch sq.)

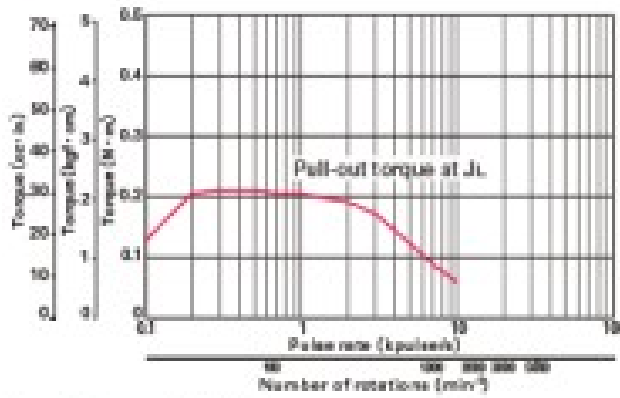
SH142□  
0.9° /step

Unipolar winding • Lead wire type

Model		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Double shafts	[N · m (oz · in.) MIN.]	A/phase	Ω /phase	mH/phase	[×10 <sup>-4</sup> kg · m <sup>2</sup> (oz · in <sup>2</sup> )]	[kg (lbs.)]
SH1421-0441	-0411	0.20 (28.32)	1.2	2.7	3.2	0.044 (0.241)	0.24 (0.53)
SH1422-0441	-0411	0.29 (41.07)	1.2	3.1	5.3	0.066 (0.361)	0.29 (0.64)
SH1424-0441	-0411	0.39 (55.23)	1.2	3.5	5.3	0.089 (0.487)	0.38 (0.84)

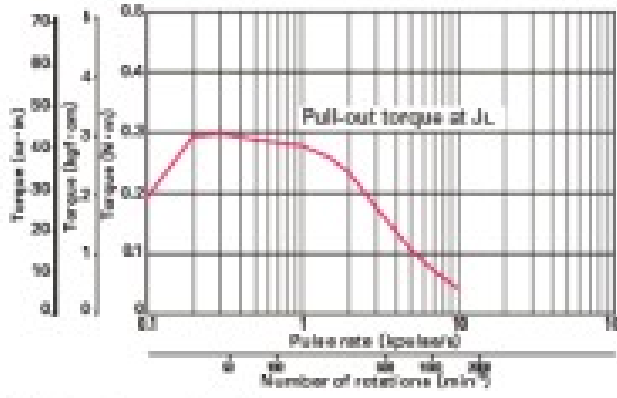
## Pulse rate-torque characteristics

● SH1421-04 □□



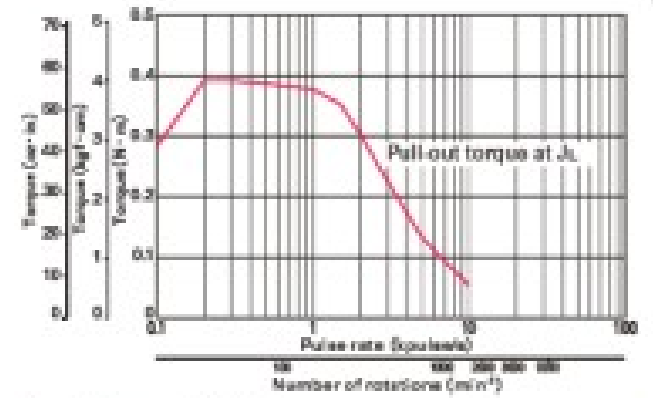
Constant current circuit  
Source voltage : DC24V · operating current : 1.2A/phase,  
2-phase energization (full-step)  
J<sub>1</sub> = [0.94×10<sup>-4</sup>kg · m<sup>2</sup> (5.14 oz · in<sup>2</sup>) Use the rubber coupling]

● SH1422-04 □□



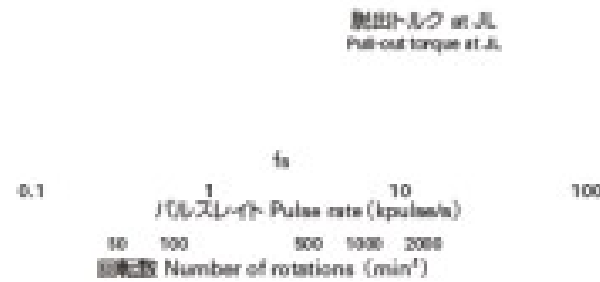
Constant current circuit  
Source voltage : DC24V · operating current : 1.2A/phase,  
2-phase energization (full-step)  
J<sub>1</sub> = [0.94×10<sup>-4</sup>kg · m<sup>2</sup> (5.14 oz · in<sup>2</sup>) Use the rubber coupling]

● SH1424-04 □□



Constant current circuit  
Source voltage : DC24V · operating current : 1.2A/phase,  
2-phase energization (full-step)  
J<sub>1</sub> = [0.94×10<sup>-4</sup>kg · m<sup>2</sup> (5.14 oz · in<sup>2</sup>) Use the rubber coupling]

The data are measured under the drive condition of our company. The drive torque may vary depending on the accuracy of customer-side equipment.

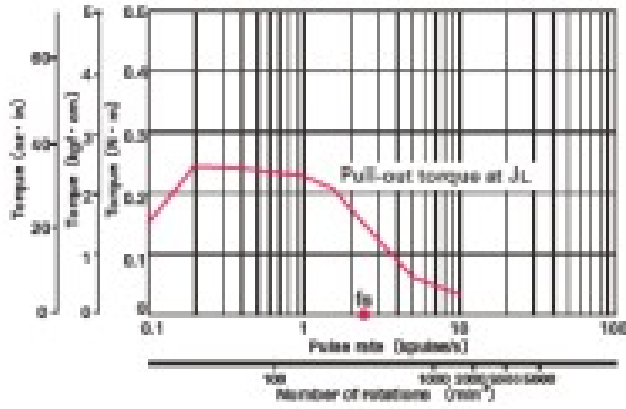


**Bipolar winding • Lead wire type**

Model		Holding torque at 2-phase energization	Rated current	Wiring resistance	Winding inductance	Rotor inertia	Mass (Weight)
Single shaft	Double shafts	[N · m (oz · in) MIN.]	A/phase	Ω /phase	mH/phase	[×10 <sup>-4</sup> kg · m <sup>2</sup> (oz · in <sup>2</sup> )]	[kg (lbs) ]
SH1421-5041	-5011	0.23 (32.5)	1	3.3	8.0	0.044 (0.24)	0.24 (0.53)
SH1421-5241	-5211	0.23 (32.5)	2	0.85	2.1	0.044 (0.24)	0.24 (0.53)
SH1422-5041	-5011	0.34 (48.1)	1	4.0	14.0	0.066 (0.36)	0.29 (0.64)
SH1422-5241	-5211	0.34 (48.1)	2	1.05	3.6	0.066 (0.36)	0.29 (0.64)
SH1424-5041	-5011	0.48 (67.9)	1	4.7	15.0	0.089 (0.49)	0.38 (0.84)
SH1424-5241	-5211	0.48 (67.9)	2	1.25	3.75	0.089 (0.49)	0.38 (0.84)

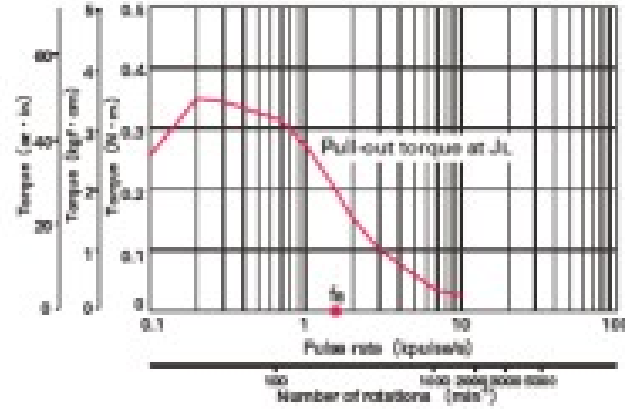
**Pulse rate-torque characteristics**

● SH1421-50 □□



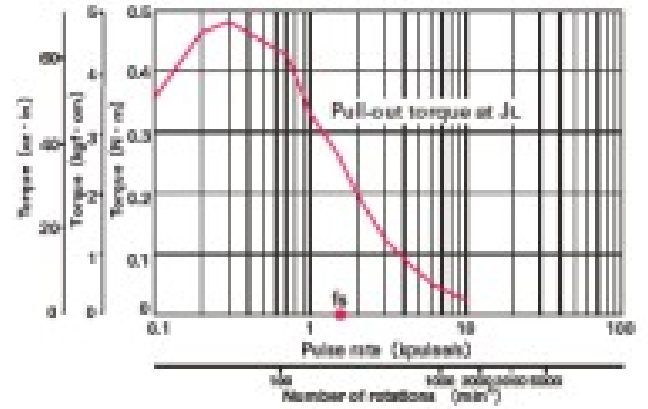
Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

● SH1422-50 □□



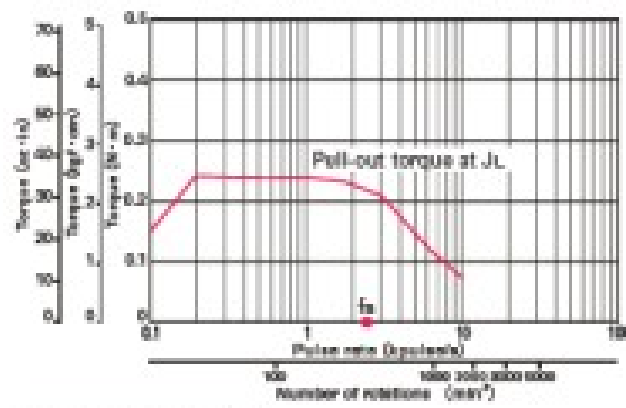
Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

● SH1424-50 □□



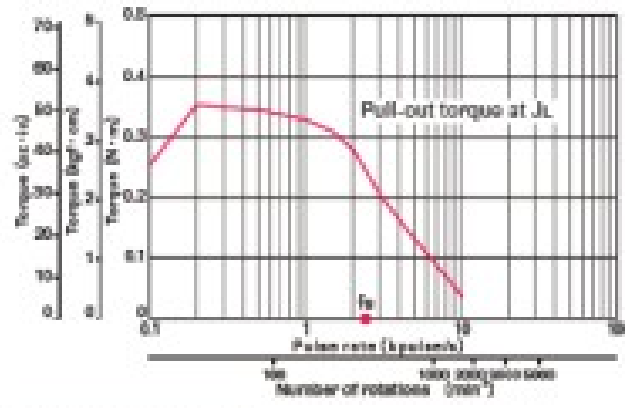
Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

● SH1421-52 □□



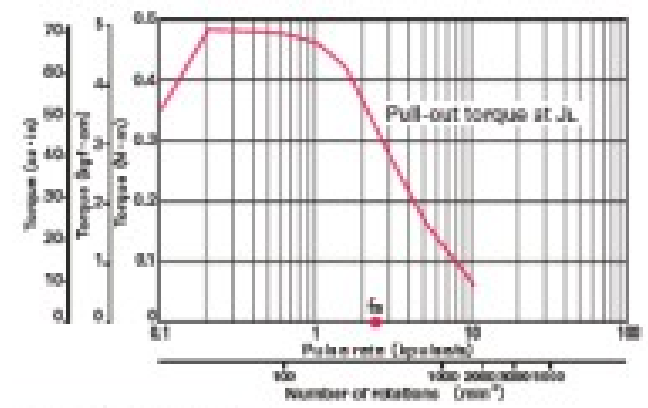
Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

● SH1422-52 □□



Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

● SH1424-52 □□



Constant current circuit  
 Source voltage : DC24V - operating current : 2A/phase,  
 2-phase energization (full-step)  
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2 (5.14 \text{oz} \cdot \text{in}^2)]$  Use the rubber coupling]  
 fs: No load maximum starting pulse rate

The data are measured under the drive condition of our company. The drive torque may vary depending on the accuracy of customer-side equipment.