

# **MLFB-Ordering data**

6SL3210-1KE31-7UF1



Client order no. : Item no. :
Order no. : Consignment no. :
Offer no. : Project :
Remarks :

Rated data		General tech. specifications		
Number of phases	3 AC	Offset factor cos φ	0.99	
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.99	
Line frequency	47 63 Hz	Sound pressure level (1m)	68 dB	
Rated current (LO)	156.00 A	Power loss	1.55 kW	
Rated current (HO)	144.00 A	Filter class (integrated)	Unfiltered	
Output				
Number of phases	3 AC	Ambient conditions		
Rated voltage	400 V	Cooling	Air cooling using an integrated fan	
Rated power IEC 400V (LO)	90.00 kW	Cooling oir requirement	0.153 m³/s (5.403 ft³/s)	
Rated power NEC 480V (LO)	100.00 hp	Cooling air requirement	, ,	
Rated power IEC 400V (HO)	75.00 kW	Installation altitude	1000 m (3280.84 ft)	
Rated power NEC 480V (HO)	75.00 hp	Ambient temperature		
Rated current (IN)	164.00 A	Operation	-20 40 °C (-4 104 °F)	
Rated current (LO)	164.00 A	Transport	-40 70 °C (-40 158 °F)	
Rated current (HO)	136.00 A	Storage	-40 70 °C (-40 158 °F)	
Max. output current	272.00 A	Relative humidity		
Pulse frequency	2.000 kHz	Max. operation 95 % RH, condensation no	95 % RH, condensation not permitted	
Output fraguency for vector control	0 240 Hz		'	
Output frequency for vector control	∪ 24∪ П2	Closed-loop control techniques		
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parameterizable Yes		
		V/f with flux current control (FC	CC) Yes	
Overload capability		V/f ECO linear / square-law	Yes	
Low Overload (LO)		Sensorless vector control	Yes	
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a 300 s cycle time		Vector control, with sensor	No	
		Encoderless torque control	No	

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a

High Overload (HO)

300 s cycle time

No

No

**Encoderless torque control** 

Torque control, with encoder



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Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	PROFINET / EtherNet/IP	
Size	FSF	Со	Connections	
Net weight	57.50 kg (126.77 lb)	Signal cable		
Width	305 mm (12.01 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AV	
Height	708 mm (27.87 in)	Line side		
Depth	357 mm (14.06 in)	Version	screw-type terminal	
Inputs / outputs		Conductor cross-section	35.00 120.00 mm² (AWG 2	
tandard digital inputs		Motor end		
Number	6	Version	Screw-type terminals	
Switching level: 0→1	11 V	Conductor cross-section	35.00 120.00 mm² (AWG 2	
Switching level: 1→0	5 V	DC link (for braking resistor)	)	
Max. inrush current	15 mA	Version	Screw-type terminals	
ail-safe digital inputs		Conductor cross-section	35.00 120.00 mm² (AWG 2	
Number	1	Line length, max.	10 m (32.81 ft)	
igital outputs		PE connection	Screw-type terminals	
Number as relay changeover contact	1	Max. motor cable length	, , , , , , , , , , , , , , , , , , ,	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	300 m (984.25 ft)	
Number as transistor	1	Unshielded	450 m (1476.38 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	Standards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low Directive 2006/95/EC	
witching threshold as digital in	out			
0→1	4 V			
1→0	1.6 V			
nalog outputs				

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^{\circ}\text{C}$ 

1 (Non-isolated output)



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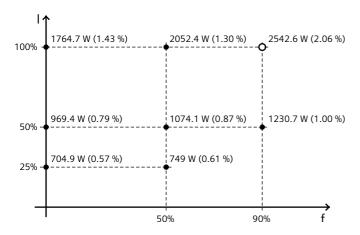
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#### Figure similar

### Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-0.50 %



The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values