

# **MLFB-Ordering data**

6SL3210-1KE13-2AB2



Figure similar

Client order no. : Order no. : Offer no. : Remarks :

ltem no. :
Consignment no. :
Project :

Rated data		General tech. specifications	
nput		Power factor λ	0.70 0.85
Number of phases	3 AC	Offset factor cos φ	0.95
Line voltage	380 480 V +10 % -20 %	Efficiency η	0.97
Line frequency	47 63 Hz	Sound pressure level (1m)	49 dB
Rated current (LO)	4.10 A	Power loss	0.05 kW
Rated current (HO)	3.20 A	Filter class (integrated)	Class A
Dutput		Ambier	
Number of phases	3 AC	Ambient conditions	
Rated voltage	400 V	Cooling	Air cooling using an integrated fan
Rated power IEC 400V (LO)	1.10 kW	Carling signature t	0.005 3/- (0.177 (43/-)
Rated power NEC 480V (LO)	1.50 hp	Cooling air requirement	0.005 m <sup>3</sup> /s (0.177 ft <sup>3</sup> /s)
Rated power IEC 400V (HO)	0.75 kW	Installation altitude	1000 m (3280.84 ft)
Rated power NEC 480V (HO)	1.00 hp	Ambient temperature	
Rated current (IN)	3.20 A	Operation	-10 40 °C (14 104 °F)
Rated current (LO)	3.10 A	Transport	-40 70 °C (-40 158 °F)
Rated current (HO)	2.20 A	Storage	-40 70 °C (-40 158 °F)
Max. output current	4.40 A	Relative humidity	
Pulse frequency	4.000 kHz	Max. operation	95 % At 40 °C (104 °F), condensatior and icing not permissible
Output frequency for vector control	0 240 Hz		
output frequency for vector control	0210112	Closed-loop	control techniques
Output frequency for V/f control	0 550 Hz	V/f linear / square-law / parame	e <b>terizable</b> Yes
		V/f with flux current control (F0	CC) Yes
Overload capability		V/f ECO linear / square-law	Yes
Low Overload (LO)		Sensorless vector control	Yes
150 % base load current IL for 3 s, followed by 110 % base load current IL for 57 s in a		Vector control, with sensor	No
300 s cycle time	e time		No

#### High Overload (HO)

200 % base load current IH for 3 s, followed by 150 % base load current IH for 57 s in a 300 s cycle time

Torque control, with encoder

No



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		1 [	Figure s	
Mechanical data		Com	Communication	
Degree of protection	IP20 / UL open type	Communication	RS485	
Size	FSAA	Connections		
Net weight	1.40 kg (3.09 lb)	Signal cable		
Width	73 mm (2.87 in)	Conductor cross-section	0.15 1.50 mm² (AWG 24 AWG 1	
Height	173 mm (6.81 in)	Line side		
Depth	155 mm (6.10 in)	Version	Plug-in screw terminals	
Inputs / out	tputs	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14	
tandard digital inputs		Motor end		
Number	6	Version	Plug-in screw terminals	
Switching level: 0→1	11 V	Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 1	
Switching level: 1→0	5 V	DC link (for braking resistor)	)	
Max. inrush current	15 mA	Version	Plug-in screw terminals	
ail-safe digital inputs		Conductor cross-section	1.00 2.50 mm² (AWG 18 AWG 14	
Number	1	Line length, max.	15 m (49.21 ft)	
igital outputs		PE connection	On housing with M4 screw	
Number as relay changeover contact	1	Max. motor cable length	on housing with wriselew	
Output (resistive load)	DC 30 V, 0.5 A	Shielded	50 m (164.04 ft)	
Number as transistor	1	Unshielded	100 m (328.08 ft)	
Output (resistive load)	DC 30 V, 0.5 A	S	Standards	
nalog / digital inputs		Compliance with standards	UL, cUL, CE, C-Tick (RCM)	
Number	1 (Differential input)			
Resolution	10 bit	CE marking	EMC Directive 2004/108/EC, Low-Volt Directive 2006/95/EC	
witching threshold as digital in	put			
0→1	4 V			
1→0	1.6 V			

Analog outputs

Number

1 (Non-isolated output)

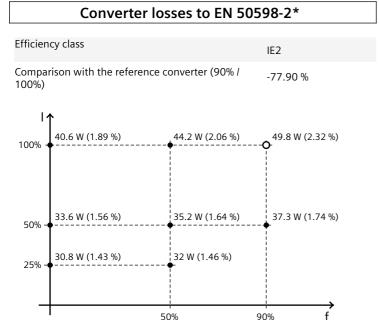
## PTC/ KTY interface

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^\circ\mathrm{C}$ 



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The percentage values show the losses in relation to the rated apparent power of the converter.

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

\*converted values



Figure similar