

56 mm sq. (2.20 inch sq.)

1.8° /step RoHS

Bipolar winding, Lead wire type

Unipolar winding, Lead wire type ▶ p. 68

Customizing

Hollow Shaft modification

Decelerator Encoder

Varies depending on the model number and quantity. Contact us for details.

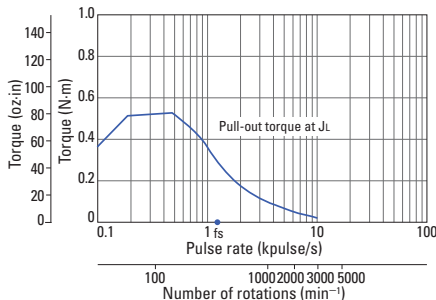
Bipolar winding, Lead wire type

Model number		Holding torque at 2-phase energization [N·m (oz·in) min.]	Rated current A/phase	Wiring resistance Ω /phase	Winding inductance mH/phase	Rotor inertia [$\times 10^{-4}$ kg·m ² (oz·in ²)]	Mass (Weight) [kg (lbs)]	Motor length (L) mm (in)	Shaft diameter (D) mm (in)	Dcut thickness (T) mm (in)
Single shaft	Dual shaft									
103H7121-5640	103H7121-5610	0.55 (77.9)	1	4.3	14.5	0.1 (0.55)	0.47 (1.04)	41.8 (1.65)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7121-5740	103H7121-5710	0.55 (77.9)	2	1.1	3.7	0.1 (0.55)	0.47 (1.04)	41.8 (1.65)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7121-5840	103H7121-5810	0.55 (77.9)	3	0.54	1.74	0.1 (0.55)	0.47 (1.04)	41.8 (1.65)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7123-5640	103H7123-5610	1.0 (141.6)	1	5.7	29.4	0.21 (1.15)	0.65 (1.43)	53.8 (2.12)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7123-5740	103H7123-5710	1.0 (141.6)	2	1.5	7.5	0.21 (1.15)	0.65 (1.43)	53.8 (2.12)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7123-5840	103H7123-5810	1.0 (141.6)	3	0.7	3.5	0.21 (1.15)	0.65 (1.43)	53.8 (2.12)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7126-5640	103H7126-5610	1.6 (226.6)	1	7.7	34.6	0.36 (1.97)	0.98 (2.16)	75.8 (2.98)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7126-5740	103H7126-5710	1.6 (226.6)	2	2	9.1	0.36 (1.97)	0.98 (2.16)	75.8 (2.98)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7126-5840	103H7126-5810	1.6 (226.6)	3	0.94	4	0.36 (1.97)	0.98 (2.16)	75.8 (2.98)	ϕ 6.35 (ϕ 0.25)	5.8 (0.23)
103H7128-5640	103H7128-5610	2.0 (283.2)	1	8.9	40.1	0.49 (2.68)	1.3 (2.87)	94.8 (3.73)	ϕ 8 (ϕ 0.31)	7.5 (0.30)
103H7128-5740	103H7128-5710	2.0 (283.2)	2	2.3	10.4	0.49 (2.68)	1.3 (2.87)	94.8 (3.73)	ϕ 8 (ϕ 0.31)	7.5 (0.30)
103H7128-5840	103H7128-5810	2.0 (283.2)	3	1.03	4.3	0.49 (2.68)	1.3 (2.87)	94.8 (3.73)	ϕ 8 (ϕ 0.31)	7.5 (0.30)

Characteristics diagram

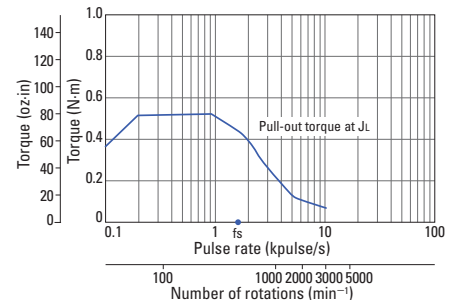
103H7121-5640 103H7121-5610

Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2$ (5.14
oz·in²) use the rubber
coupling]
 f_s : Maximum self-start
frequency when not
loaded



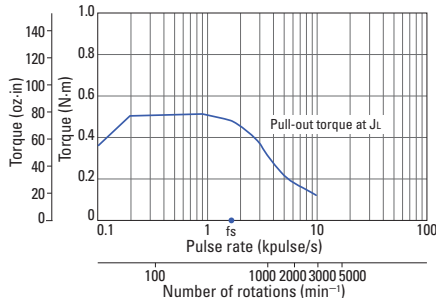
103H7121-5740 103H7121-5710

Constant current circuit
Source voltage: 24 VDC
Operating current:
2 A/phase, 2-phase
energization (full-step)
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2$ (5.14
oz·in²) use the rubber
coupling]
 f_s : Maximum self-start
frequency when not
loaded



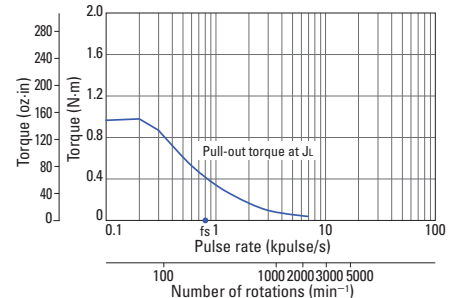
103H7121-5840 103H7121-5810

Constant current circuit
Source voltage: 24 VDC
Operating current:
3 A/phase, 2-phase
energization (full-step)
 $J_L = [0.94 \times 10^{-4} \text{kg} \cdot \text{m}^2$ (5.14
oz·in²) use the rubber
coupling]
 f_s : Maximum self-start
frequency when not
loaded



103H7123-5640 103H7123-5610

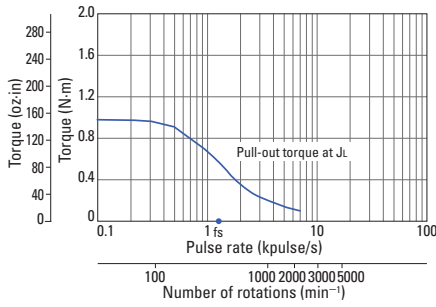
Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
 $J_L = [2.6 \times 10^{-4} \text{kg} \cdot \text{m}^2$ (14.22
oz·in²) use the rubber
coupling]
 f_s : Maximum self-start
frequency when not
loaded



Characteristics diagram

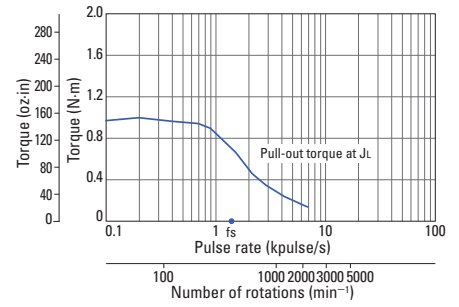
103H7123-5740 103H7123-5710

Constant current circuit
Source voltage: 24 VDC
Operating current:
2 A/phase, 2-phase
energization (full-step)
 $J_L=[2.6 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (14.22
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



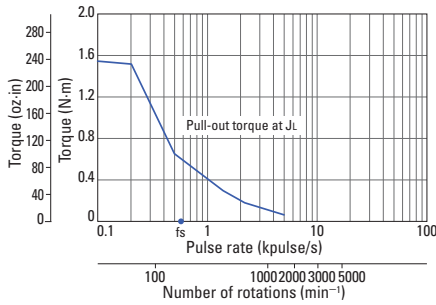
103H7123-5840 103H7123-5810

Constant current circuit
Source voltage: 24 VDC
Operating current:
3 A/phase, 2-phase
energization (full-step)
 $J_L=[2.6 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (14.22
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



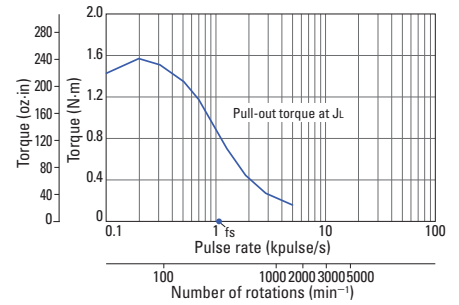
103H7126-5640 103H7126-5610

Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
 $J_L=[2.6 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (14.22
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



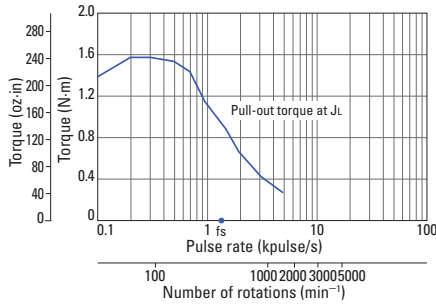
103H7126-5740 103H7126-5710

Constant current circuit
Source voltage: 24 VDC
Operating current:
2 A/phase, 2-phase
energization (full-step)
 $J_L=[2.6 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (14.22
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



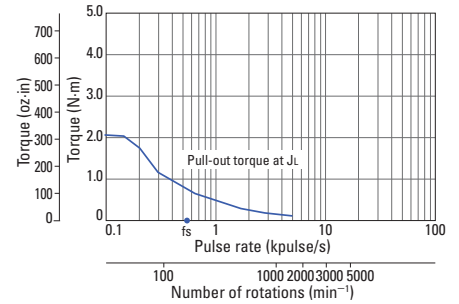
103H7126-5840 103H7126-5810

Constant current circuit
Source voltage: 24 VDC
Operating current:
3 A/phase, 2-phase
energization (full-step)
 $J_L=[7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (40.46
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



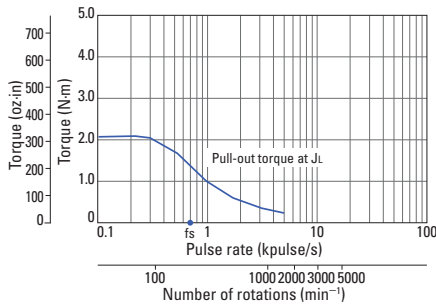
103H7128-5640 103H7128-5610

Constant current circuit
Source voltage: 24 VDC
Operating current:
1 A/phase, 2-phase
energization (full-step)
 $J_L=[7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (40.46
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



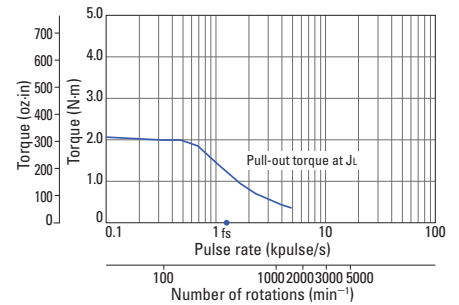
103H7128-5740 103H7128-5710

Constant current circuit
Source voltage: 24 VDC
Operating current:
2 A/phase, 2-phase
energization (full-step)
 $J_L=[7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (40.46
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded

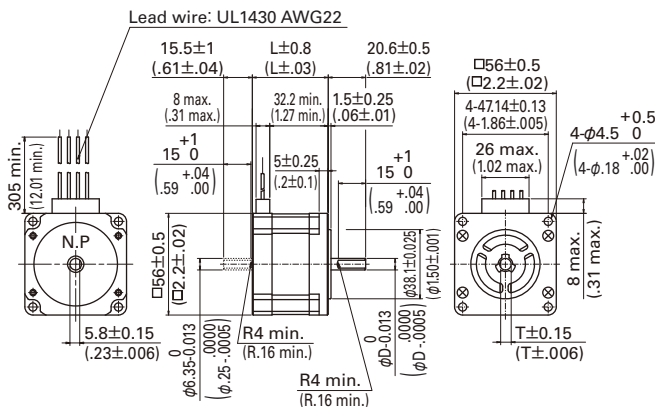


103H7128-5840 103H7128-5810

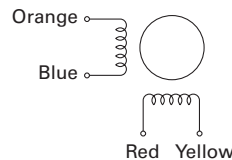
Constant current circuit
Source voltage: 24 VDC
Operating current:
3 A/phase, 2-phase
energization (full-step)
 $J_L=[7.4 \times 10^{-4} \text{kg}\cdot\text{m}^2$ (40.46
oz-in²) use the rubber
coupling]
fs: Maximum self-start
frequency when not
loaded



Dimensions [Unit: mm (inch)]



Internal wiring

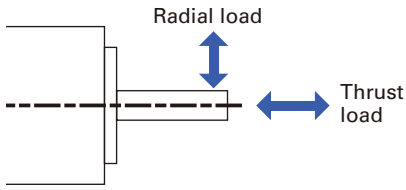


Compatible drivers

Driver is not included.

If you require assistance finding a driver, contact us for details.

Allowable Radial/Thrust Load



Flange size	Model number	Distance from end of shaft : mm (in)				Thrust load N (lbs)
		0	5	10	15	
Radial load : N (lbs)						
14 mm sq. (0.55 in sq.)	SH2141	10 (2.25)	11 (2.47)	13 (2.92)	-	0.7 (0.16)
28 mm sq. (1.10 in sq.)	SH228 □	42 (9)	48 (10)	56 (12)	66 (14)	3 (0.67)
35 mm sq. (1.38 in sq.)	SH353 □	40 (8)	50 (11)	67 (15)	98 (22)	10 (2.25)
42 mm sq. (1.65 in sq.)	103H52 □□	22 (4)	26 (5)	33 (7)	46 (10)	10 (2.25)
	SH142 □					
50 mm sq. (1.97 in sq.)	103H670 □	71 (15)	87 (19)	115 (25)	167 (37)	15 (3.37)
56 mm sq. (2.20 in sq.)	103H712 □	85 (19)	105 (23)	138 (31)	200 (44)	15 (3.37)
	103H7128					
60 mm sq. (2.36 in sq.)	103H782 □	70 (15)	87 (19)	114 (25)	165 (37)	20 (4.50)
	SH160 □					
86 mm sq. (3.39 in sq.)	SM286 □	167 (37)	193 (43)	229 (51)	280 (62)	60 (13.488)
	SH286 □					
86 mm sq. (3.39 in sq.)	103H822 □	191 (43)	234 (53)	301 (68)	421 (95)	60 (13.488)
φ 106 mm (φ 4.17 in)	103H8922 □	321 (72)	356 (79)	401 (90)	457 (101)	100 (22.48)

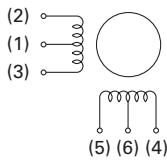
Internal Wiring and Rotation Direction

Unipolar winding

Connector type Model number: 103H52 □□

Internal wire connection

() connector pin number



Direction of motor rotation

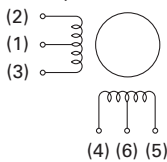
When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

Exciting order	Connector pin number				
	(1.6)	(5)	(3)	(4)	(2)
1	+	-	-	-	-
2	+	-	-	-	-
3	+	-	-	-	-
4	+	-	-	-	-

Connector type Model number: 103H782 □□

Internal wire connection

() connector pin number



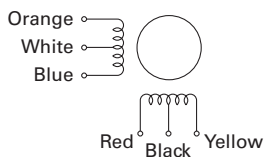
Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

Exciting order	Connector pin number				
	(1.6)	(4)	(3)	(5)	(2)
1	+	-	-	-	-
2	+	-	-	-	-
3	+	-	-	-	-
4	+	-	-	-	-

Lead wire type

Internal wire connection



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

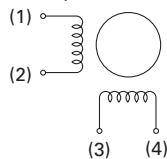
Exciting order	Lead wire color				
	White & black	Red	Blue	Yellow	Orange
1	+	-	-	-	-
2	+	-	-	-	-
3	+	-	-	-	-
4	+	-	-	-	-

Bipolar winding

Connector type

Internal wire connection

() connector pin number, terminal block number



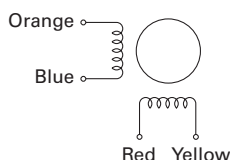
Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

Exciting order	Connector pin number, terminal block number				
	(3)	(2)	(4)	(1)	
1	-	-	+	+	
2	+	-	-	+	
3	+	+	-	-	
4	-	+	+	-	

Lead wire type

Internal wire connection



Direction of motor rotation

When excited by a direct current in the order shown below, the direction of rotation is clockwise as viewed from the output shaft side.

Exciting order	Lead wire color			
	Red	Blue	Yellow	Orange
1	-	-	+	+
2	+	-	-	+
3	+	+	-	-
4	-	+	+	-

General Specifications

Motor model number	SH2141	SH228 □	SH353 □	SS242 □	SH142 □	103H52 □□	SS250 □	103H67 □□	103H712 □
Type	-								
Operating ambient temperature	- 10°C to + 50°C								
Conversation temperature	- 20°C to + 65°C								
Operating ambient humidity	20 to 90% RH (no condensation)								
Conversation humidity	5 to 95% RH (no condensation)								
Operation altitude	1000 m (3281 feet) max. above sea level								
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 150 m/s ² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.								
Impact resistance	500 m/s ² of acceleration for 11 ms with half-sine wave applying three times for X, Y, and Z axes each, 18 times in total.								
Insulation class	Class B (+130°C)								
Withstandable voltage	At normal temperature and humidity, no failure with 500 VAC @50/60 Hz applied for one minute between motor winding and frame.							At normal temperature and humidity, no failure with 1000 VAC @50/60 Hz applied for one minute between motor winding and frame.	
Insulation resistance	At normal temperature and humidity, not less than 100 MΩ between winding and frame by 500 VDC megger.								
Protection grade	IP40								
Winding temperature rise	80 K max. (Based on Sanyo Denki standard)								
Static angle error	± 0.09°				± 0.054°		± 0.09°		
Thrust play *1	0.075 mm (0.003 in) max. (load: 0.35 N (0.08 lbs))	0.075 mm (0.003 in) max. (load: 1.5 N (0.34 lbs))	0.075 mm (0.003 in) max. (load: 5 N (1.12 lbs))	0.075 mm (0.003 in) max. (load: 4 N (0.9 lbs))	0.075 mm (0.003 in) max. (load: 5 N (1.12 lbs))	0.075 mm (0.003 in) max. (load: 5 N (1.12 lbs))	0.075 mm (0.003 in) max. (load: 4 N (0.9 lbs))	0.075 mm (0.003 in) max. (load: 10 N (2.25 lbs))	0.075 mm (0.003 in) max. (load: 10 N (2.25 lbs))
Radial play *2	0.025 mm (0.001 in) max. (load: 5 N (1.12 lbs))								
Shaft runout	0.025 mm (0.001 in)								
Concentricity of mounting pilot relative to shaft	φ 0.05 mm (φ 0.002 in)	φ 0.05 mm (φ 0.002 in)	φ 0.075 mm (φ 0.003 in)	φ 0.075 mm (φ 0.003 in)	φ 0.05 mm (φ 0.002 in)	φ 0.05 mm (φ 0.002 in)	φ 0.075 mm (φ 0.003 in)	φ 0.075 mm (φ 0.003 in)	φ 0.075 mm (φ 0.003 in)
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)
Direction of motor mounting	Can be freely mounted vertically or horizontally								

Motor model number	SH160 □	103H78 □□	SH286 □	103H8922 □	SM286 □	103H712 □ -6 □□ 0 CE Model	103H822 □ -6 □□ 0 CE Model	103H8922 □ -63 □ 1 CE Model	
Type	-				S1 (continuous operation)				
Operating ambient temperature	- 10°C to + 50°C				- 10°C to + 40°C				
Conversation temperature	- 20°C to + 65°C				- 20°C to + 60°C				
Operating ambient humidity	20 to 90% RH (no condensation)				95% max.: 40°C max., 57% max.: 50°C max., 35% max.: 60°C max. (no condensation)				
Conversation humidity	5 to 95% RH (no condensation)								
Operation altitude	1000 m (3280 feet) max. above sea level								
Vibration resistance	Vibration frequency 10 to 500 Hz, total amplitude 1.52 mm (10 to 70 Hz), vibration acceleration 150 m/s ² (70 to 500 Hz), sweep time 15 min/cycle, 12 sweeps in each X, Y and Z direction.								
Impact resistance	500 m/s ² of acceleration for 11 ms with half-sine wave applying three times for X, Y and Z axes each, 18 times in total.								
Insulation class	Class B (+130°C)				Class F (+155°C)		Class B (+130°C)		
Withstandable voltage	At normal temperature and humidity, no failure with 1000 VAC @50/60 Hz applied for one minute between motor winding and frame.				At normal temperature and humidity, no failure with 1500 VAC @50/60 Hz applied for one minute between motor winding and frame.				
Insulation resistance	At normal temperature and humidity, not less than 100 MΩ between winding and frame by 500 VDC megger.								
Protection grade	IP40				IP43				
Winding temperature rise	80 K max. (Based on Sanyo Denki standard)								
Static angle error	± 0.054°		± 0.09°						
Thrust play *1	0.075 mm (0.003 in) max. (load: 10 N (2.25 lbs))								
Radial play *2	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 10 N (2.25 lbs))	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 5 N (1.12 lbs))	0.025 mm (0.001 in) (load: 10 N (2.25 lbs))	
Shaft runout	0.025 mm (0.001 in)								
Concentricity of mounting pilot relative to shaft	φ 0.075 mm (φ 0.003 in)								
Squareness of mounting surface relative to shaft	0.1 mm (0.004 in)	0.075 mm (0.003 in)	0.15 mm (0.006 in)	0.1 mm (0.004 in)	0.15 mm (0.006 in)	0.075 mm (0.003 in)	0.1 mm (0.004 in)	0.1 mm (0.004 in)	
Direction of motor mounting	Can be freely mounted vertically or horizontally								

*1 Thrust play: Shaft displacement under axial load.

*2 Radial play: Shaft displacement under radial load applied 1/3rd of the length from the end of the shaft.

Safety standards

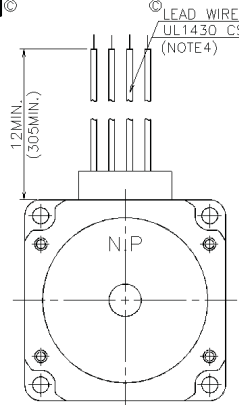
Model Number: **SM286** □ CE/UL marked models

CE (TÜV)	Standard category		Applicable standard
	Low-voltage directives		EN60034-1, EN60034-5
UL	Acquired standards	Applicable standard	File No.
	UL	UL1004-1, UL1004-6	E179832
	UL for Canada	CSA C22.2 No.100	

Model Number: **103H712** □ -6 □□ 0, **103H822** □ -6 □□ 0, **103H8922** □ -63 □ 1 CE marked model

CE (TÜV)	Standard category		Applicable standard
	Low-voltage directives		EN60034-1, EN60034-5

RoHS



RATED CHARACTERISTICS

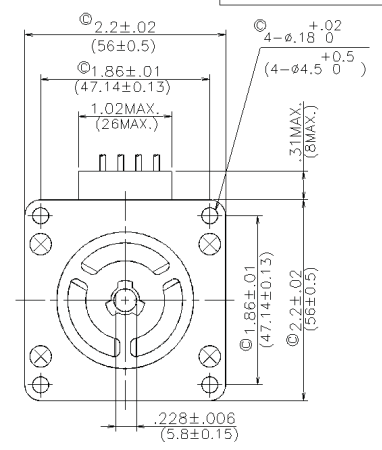
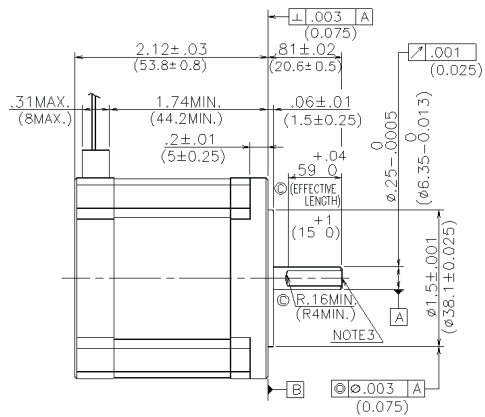
PHASES	2
STEP ANGLE	1.8 °
VOLTS	3 V[DC]
AMPS	2 A/phase
D.C RESISTANCE	1.5 Ω±10% at 25 °C
COIL INDUCTANCE	7.5 mH±20% at 1 kHz, 1 V[rms]
Ⓢ HOLDING TORQUE	141.6 oz·in (1.0 N·m)MIN. at I=2 A/phase 2Ex.
NOTE1. PULL OUT TORQUE	110 oz·in (0.78 N·m)MIN. at 200 pulse/s Ⓢ INERTIAL LOAD 14.2 oz·in ² (2.6×10 ⁻⁴ kg·m ²) Ⓢ (INERTIA OF RUBBER COUPLING IS INCLUDED.)
NOTE1. MAX. STARTING RATE	1000 pulse/sMIN. at NO LOAD
NOTE1. MAX. SLEWING RATE	1050 pulse/sMIN. at NO LOAD
NOTE2. POSITIONAL ACCURACY	±0.054 ° (0.108° SPREAD MAX.) 2Ex.
COIL TEMPERATURE RISE	80 K MAX.
ROTOR INERTIA	1.15 oz·in ² (0.21×10 ⁻⁴ kg·m ²) NOMINAL
INSULATION CLASS	B
Ⓢ ALLOWABLE THRUST LOAD	15 N
Ⓢ ALLOWABLE RADIAL LOAD	56 N LOAD TO SHAFT END.

NOTE1. SANYO STANDARD 2PHASE EXCITATION DRIVE CIRCUIT WAS USED.
E=24 V[DC], I=2 A/phase.(AVERAGE VALUE)

NOTE2. MOUNT A MOTOR ON 6.3×6.3×.24t (160×160×6t) ALUMINUM HEAT SINK AND ENERGIZE A COIL AT 2 PHASE EXCITATION, I=2 A/phase CONSTANT.

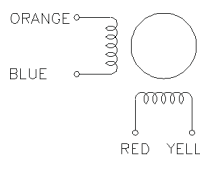
NOTE3. CENTER HOLE ON THE SHAFT END IS NOT ALWAYS MADE.

Ⓢ NOTE4. A COLOR SCHEME OF LEAD WIRE OF MOTOR'S OUTLET IS DISCRETION.



CONNECTION

DIRECTION OF ROTATION



WHEN A MOTOR IS SEQUENCED AS SHOWN IN THE TABLE BELOW, THE SHAFT ROTATION MUST BE CLOCKWISE WHEN YOU SEE FROM SURFACE [B] SIDE.

	RED	BLUE	YELLOW	ORANGE
1	⊖	⊖	⊕	⊕
2	⊕	⊖	⊖	⊕
3	⊖	⊕	⊕	⊖
4	⊕	⊕	⊖	⊖

C E0069269 05-05-31		REV. 1	DESIGNED BY K. UCHIMURA 05-06-06	DATE 05-06-06	REV. TITLE
B E0054131 03-04-11		REV. 1	DESIGNED BY K. UCHIMURA 05-06-06	DATE 05-06-06	STEPPING MOTOR
A NEW DESIGN 03-01-09		REV. 1	DESIGNED BY K. UCHIMURA 05-05-31	DATE 05-05-31	
山洋電気株式会社 SANYO DENKI CO., LTD.			103H7123-5740		REV. C